Characterizing adversarial examples in deep networks with convolutional filter statistics

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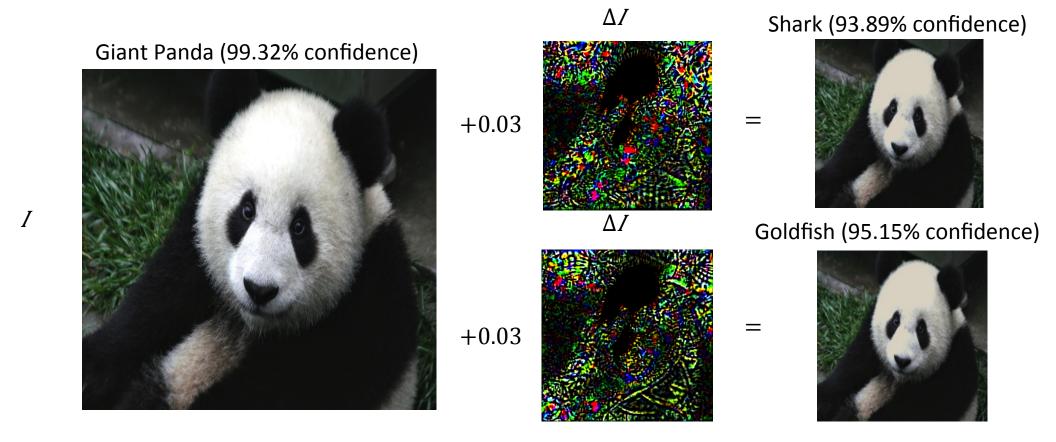
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Fooling a deep network (Szegedy et al. 2013)

• Optimizing a delta from the image to maximize a class prediction $f \downarrow c(x)$ $\max_{\tau} \Delta I \ f \downarrow c(I + \Delta I) - \lambda ||\Delta I|| 1/2$

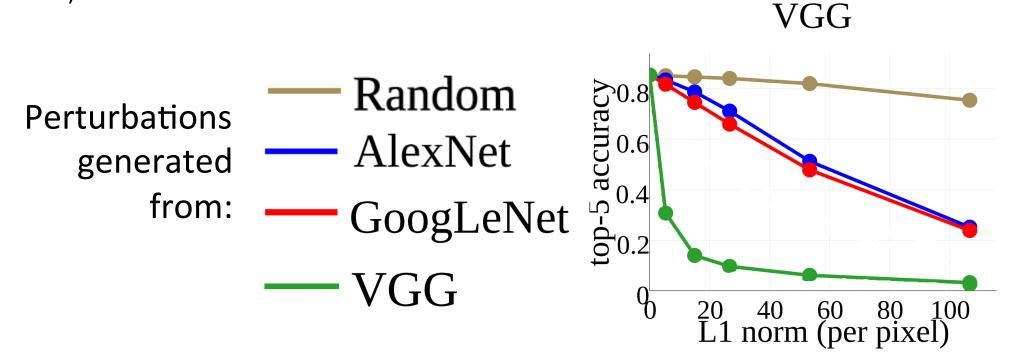


(Szegedy et al. 2013, Goodfellow et al. 2014, Nguyen et al. 2015)

Generalization of fooling

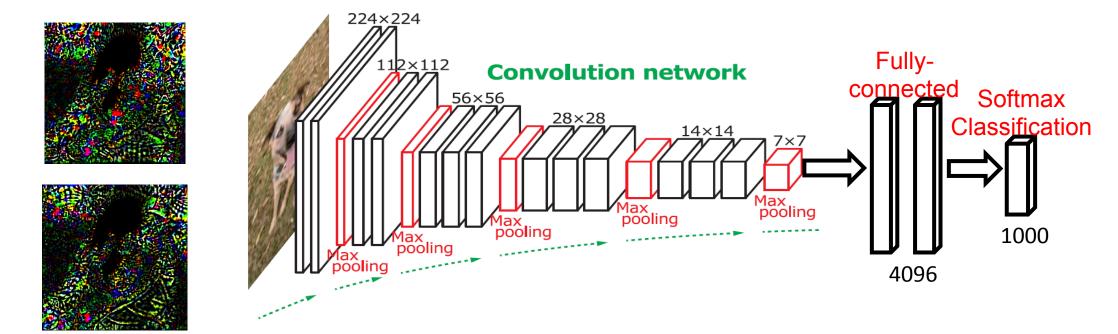
- Adversarial examples are not random
- They generalize across networks!

• Use one algorithm to generate perturbations and test on others (Luo et al. 2016)



Closer Examination of Perturbations

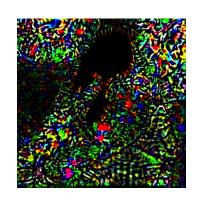
- Two networks used in analysis:
 - AlexNet (2012 state-of-the-art, 16% error on ImageNet challenge)
 - VGG Network (2014-2015 state-of-the-art, 7% error on ImageNet challenge)
 - First part on VGG, second part on both

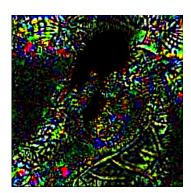


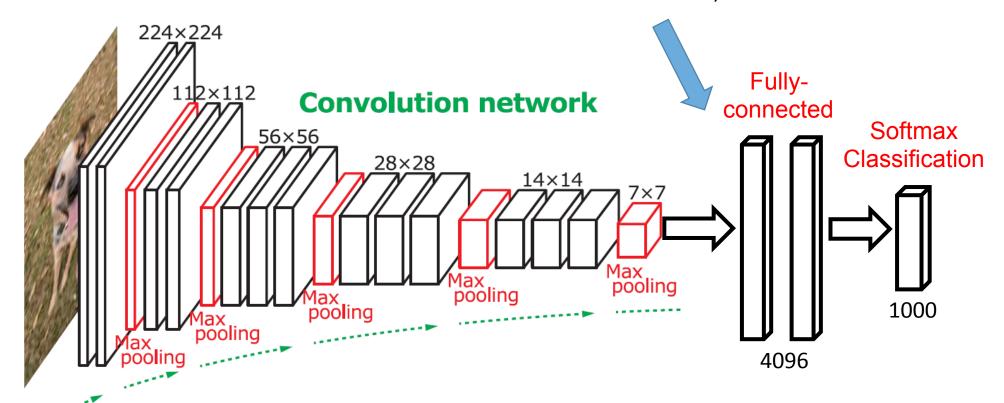
Generate Insights: Explore at the End

No convolution anymore Close to final output

Use PCA (NN = linear + transformation)

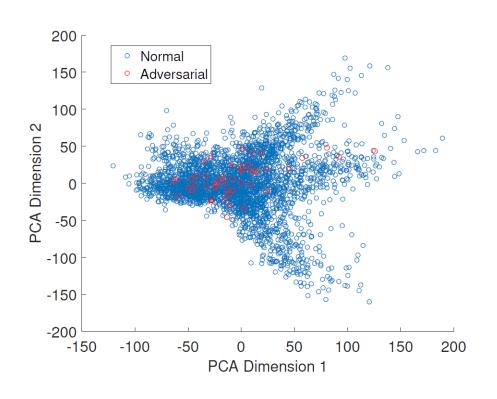


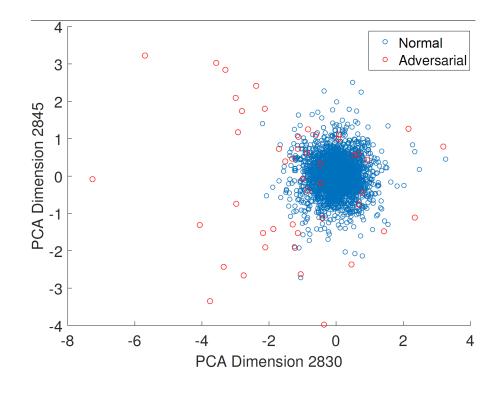




Corruption Traces before the Fully-Connected Layer

• Do a PCA on layer-14 features (after the last convolutional layer)



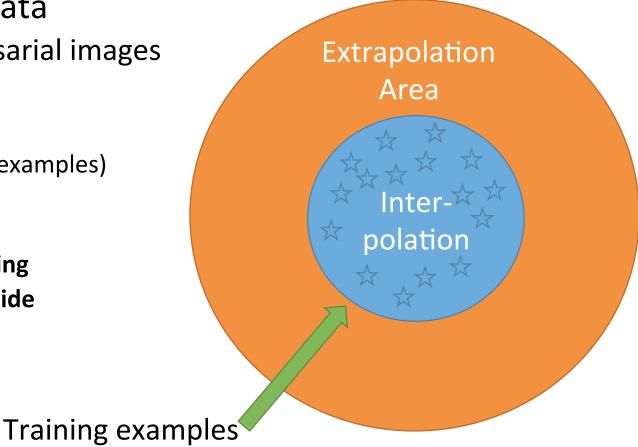


Fundamental Aspect of ML

 Machine learning works only on the test data if it's sampled from the same distribution with training data

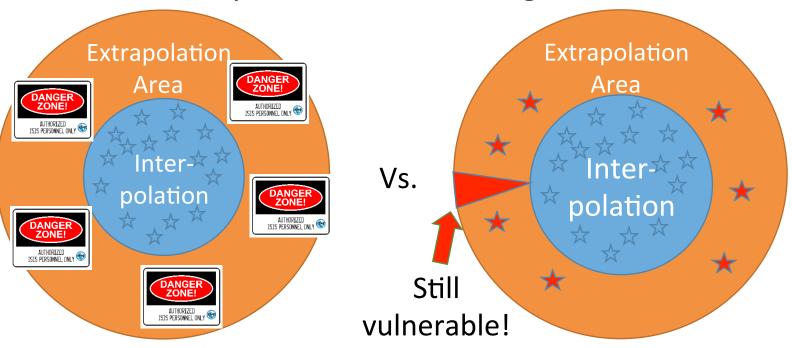
 No good result expected on adversarial images since never trained on it

- Solution?
 - Enlarge training set (add adversarial examples) (Goodfellow et al. 2014)
 - Led to many GAN-type approaches
 - Or just detect the boundary of training distribution and refuse to work outside

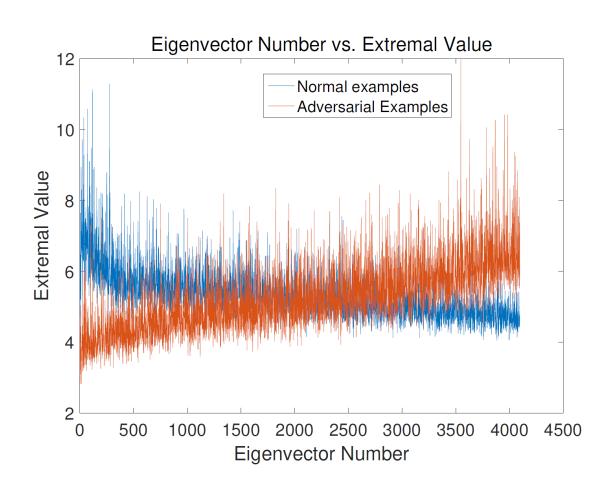


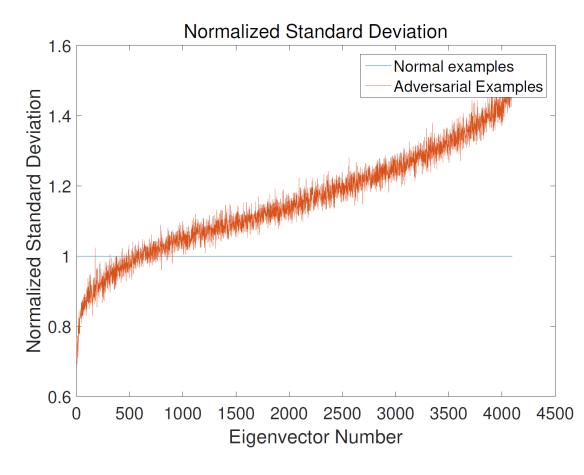
A conservative approach

- Never do extrapolation!
 - Instead, identify intruder attempts for doing so
 - Has been studied in machine learning, e.g. self-aware learning (Li et al. 2008)
- Instead of "adding adversarial examples back to training"
 - Which never ends!



Back to Difference between Normal and Adversarial Examples



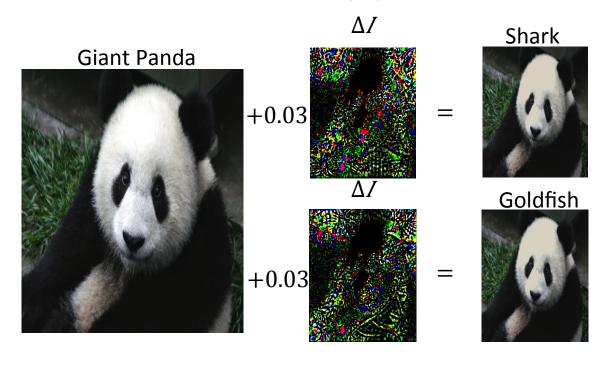


How to observe distributional statistics from a single image?

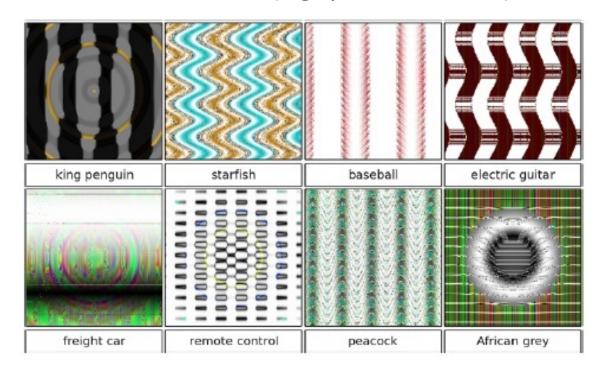
- An image is a distribution of pixels
- Each convolutional layer output is a distribution of pixels
 - K-dimensional distribution on k filter outputs
- Try not to use features to train directly (overfitting!)
- Instead, collect statistics:
 - Mean absolute value of normalized PCA coefficients
 - Minimal and maximal values
 - 25-th, 50-th and 75-th percentiles

Visualization: 2 types of adversarials

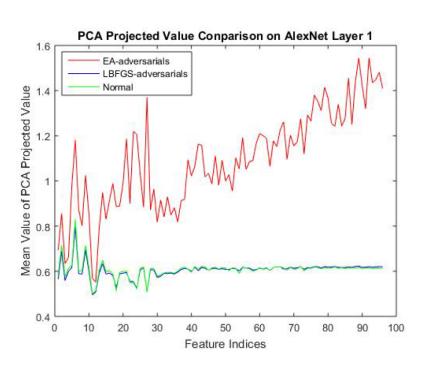
LBFGS-Adversarials (Nguyen et al. 2015)

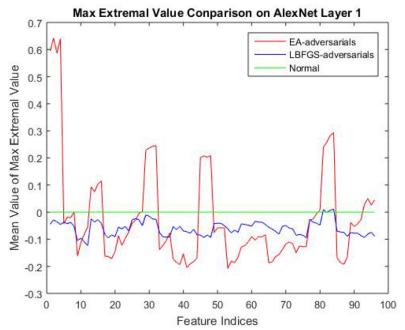


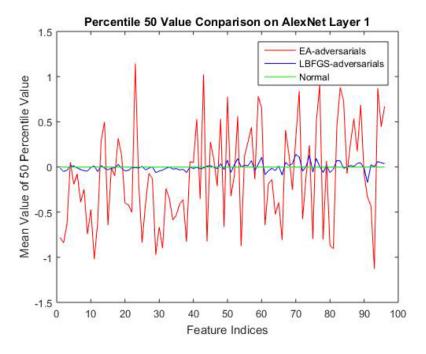
EA-Adversarials (Nguyen et al. 2015)



Visualization:







Single-Layer Results

- Single-layer results are OK, not fantastic
 - Imaginable with oversimplified features
 - EA-Adversarials much easier to detect

Table 1. Classification Result with AlexNet for Normal vs. LBFGS-adversarials

Network Layer	2nd	3rd	4th
Accuracy	57.5 ± 0.7	67.3 ± 0.7	70.9 ± 0.6
Network Layer	5th	6th	
Accuracy	74.9 ± 0.9	78.95 ± 0.6	

Table 3. Classification Result for Normal vs. EA-Adversarials

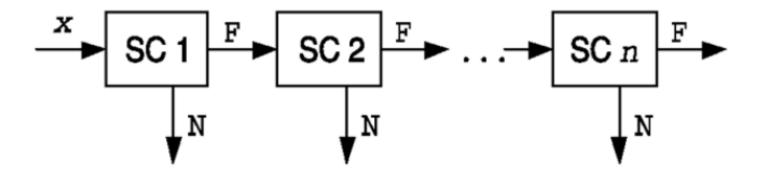
Layer	2nd	3rd	4th
Accuracy	93.45 ± 0.69	98.3 ± 0.73	97.9 ± 0.57

Table 2. Classification Result with VGG-16 for Normal vs. LBFGS-Adersarials

Network Layer	2nd	3rd	4th
Accuracy	72.1 ± 0.7	84.1 ± 0.7	80.3 ± 0.6
Network Layer	5th	6th	7th
Accuracy	81.4 ± 0.9	74.3 ± 0.6	73.9 ± 0.6
Network Layer	8th	9th	10th
Accuracy	74.2 ± 0.7	71.2 ± 0.7	74.3 ± 0.8

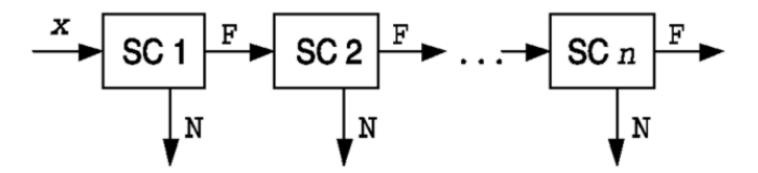
Classifier Cascade

- Proposed by Viola-Jones in 2001 for face detection
- Idea: discard large amount of examples that are simple to classify
- Leave those hard to classify to the next (more expensive) stage

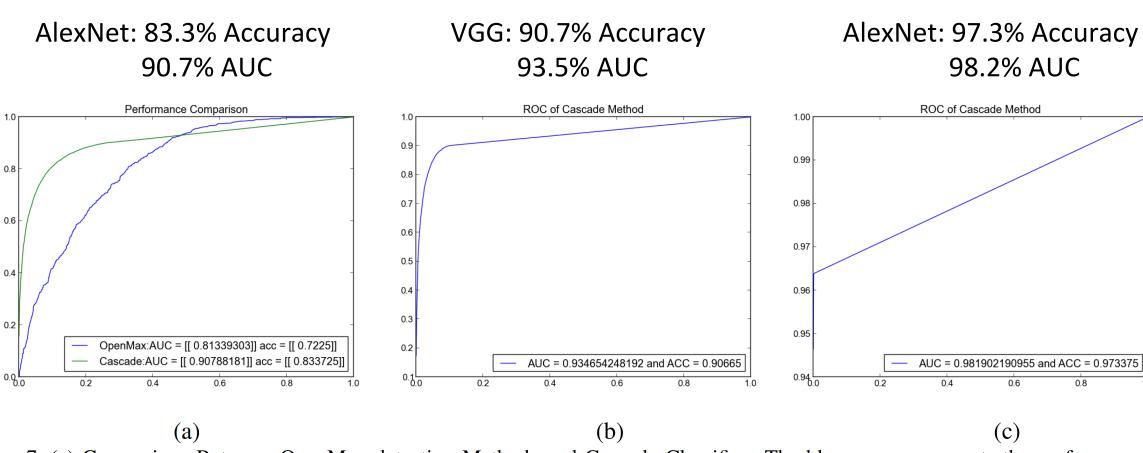


Classifier Cascade

- 1 classifier for each convolutional layer
 - Classify on layer 1:
 - Normal: do not continue
 - Unsure: go to layer 2
 - Classify on layer 2...



Result

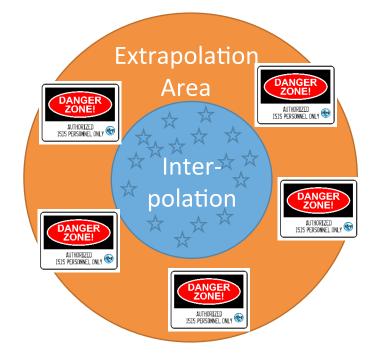


EA-Adversarials

LBFGS Adversarials

Figure 7. (a) Comparison Between OpenMax detection Methods and Cascade Classifier: The blue curve represents the performace of OpenMax Method, and green curve represents the performace for Cascade Classifier.(b) Overall ROC Performance Curve of Cascade Classifier Trained on VGG-16 Network. (c) Overall ROC of data generated from EA-adversarials dataset on AlexNet.

Conclusion





- A different approach geared toward AI safety
 - Conservative
 - Avoids extrapolation
 - Try to perform "distribution tests" to test whether an example comes from input distribution
 - Classifier cascades on convolutional filter statistics work well
- Future work:
 - Generative Adversarial Network (GAN) -type approach to detect intrusion

Image Recovery for LBFGS-adversarials

- Insight: LBFGS adversarials attacks the extremal value of gradient output
- This is very specific to manipulating pixels to lower the magnitude of certain outputs
- One can counter even with simple average filtering

Approach	Top-5 Accuracy	
	(Recovered Images)	
Original Image (Non-corrupted)	86.5%	
3×3 Average Filter	73.0%	
5×5 Average Filter	68.0%	
Foveation (Object Crop MP) [16]	82.6%	

Another side of the story

bell pepper (946), score 0.848



Noise std = 16 **bell pepper (946), score 0.841**



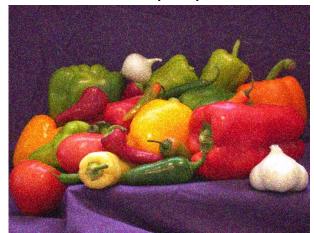
Noise std = 32 **bell pepper (946), score 0.531**



Noise std = 40 **bell pepper (946), score 0.294**



Noise std = 48 cucumber, cuke (944), score 0.175



 It's also not that hard to contaminate CNN!